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STANFORD RESEARCH INST MENLO PARK CALIF
SIMULATION OF EARTH PENETRATION LOADS. (U)
SEP 76 J D COLTON, R E EMERSON, H E LINDBERG

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SIMULATION OF EARTH PENETRATION LOADS

Stanford Research Institute
333 Ravenswood Avenue
Menlo Park, California 94025

September 1976

Final Report

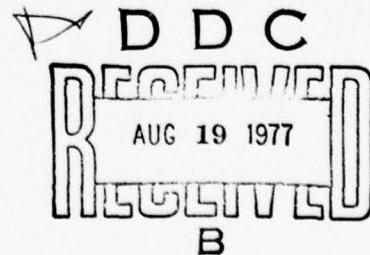
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20. ABSTRACT (Continued)

test to test by simple adjustments of the device. The technique allows hard-wired measurement of the applied load and the response of the structure. A series of initial calibration tests conducted without a model structure indicates that the device operates properly.

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PREFACE

The original objective of this contract was to devise a means of creating a well-defined dust cloud for testing heat shield materials in dust erosion. This work has been completed and the final report, entitled "The Feasibility of Generation of Linear Particulate Clouds," has been submitted. The contract has been modified to include a task to develop a technique for simulating the impact loads on earth penetrating structures. This final report describes the experimental apparatus constructed for that purpose and some initial test results. The contract monitor was Mr. M. J. Rubenstein of DNA. Technical assistance was also provided by Lt. R. Nibe of DNA.

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**Conversion factors for U. S. customary
to metric (SI) units of measurement.**

To Convert From	To	Multiply By
angstrom	meters (m)	1. 000 000 X E -10
atmosphere (normal)	kilo pascal (kPa)	1. 013 25 X E +2
bar	kilo pascal (kPa)	1. 000 000 X E +2
barn	meter ² (m ²)	1. 000 000 X E -28
British thermal unit (thermochemical)	joule (J)	1. 054 350 X E +3
calorie (thermochemical)	joule (J)	4. 184 000
cal (thermochemical)/cm ²	mega joule/m ² (MJ/m ²)	4. 184 000 X E -2
curie	*giga becquerel (GBq)	3. 700 000 X E +1
degree (angle)	radian (rad)	1. 745 329 X E -2
degree Fahrenheit	degree kelvin (K)	$t_K = (t^{\circ}F + 459.67)/1.8$
electron volt	joule (J)	1. 602 19 X E -19
erg	joule (J)	1. 000 000 X E -7
erg/second	watt (W)	1. 000 000 X E -7
foot	meter (m)	3. 048 000 X E -1
foot-pound-force	joule (J)	1. 355 818
gallon (U. S. liquid)	meter ³ (m ³)	3. 785 412 X E -3
inch	meter (m)	2. 540 000 X E -2
jerk	joule (J)	1. 000 000 X E +9
joule/kilogram (J/kg) (radiation dose absorbed)	Gray (Gy)	1. 000 000
kilotons	terajoules	4. 183
kip (1000 lbf)	newton (N)	4. 448 222 X E +3
kip/inch ² (ksi)	kilo pascal (kPa)	6. 894 757 X E +3
ktag	newton-second/m ² (N-s/m ²)	1. 000 000 X E +2
micron	meter (m)	1. 000 000 X E -6
mil	meter (m)	2. 540 000 X E -5
mile (international)	meter (m)	1. 609 344 X E +3
ounce	kilogram (kg)	2. 834 952 X E -2
pound-force (lbs avoirdupois)	newton (N)	4. 448 222
pound-force inch	newton-meter (N·m)	1. 129 848 X E -1
pound-force/inch	newton/meter (N/m)	1. 751 268 X E +2
pound-force/foot ²	kilo pascal (kPa)	4. 788 026 X E -2
pound-force/inch ² (psi)	kilo pascal (kPa)	6. 894 757
pound-mass (lbm avoirdupois)	kilogram (kg)	4. 535 924 X E -1
pound-mass-foot ² (moment of inertia)	kilogram-meter ² (kg·m ²)	4. 214 011 X E -2
pound-mass/foot ³	kilogram/meter ³ (kg/m ³)	1. 601 846 X E +1
rad (radiation dose absorbed)	**Gray (Gy)	1. 000 000 X E -2
roentgen	coulomb/kilogram (C/kg)	2. 579 760 X E -4
shake	second (s)	1. 000 000 X E -8
slug	kilogram (kg)	1. 459 390 X E +1
torr (mm Hg, 0° C)	kilo pascal (kPa)	1. 333 22 X E -1

*The becquerel (Bq) is the SI unit of radioactivity; 1 Bq = 1 event/s.

**The Gray (Gy) is the SI unit of absorbed radiation.

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INTRODUCTION AND BACKGROUND

As part of the development of earth-penetrating weapons, the impact response of the penetrator casing must be understood so that it can be designed to stay intact and allow penetration of the target to the required depth. This report describes the work under contract DNA001-75-C-0257, in which a technique for simulating the impact loads on earth penetrator structures was developed.*

The immediate use for a simulation technique is to apply well-defined loads to scale model structures. The response data obtained can be used to verify mathematical analysis of the penetrator response. A simulation technique would also be useful for loading full-scale structures in the elastic range so that many tests could be performed on a single structure. Therefore, the design of the loading device developed here for scale model structures was made suitable for fabrication in a larger size for loading full-scale structures.

For angle of attack impacts, large strains and failures in penetrator structures have been observed to occur at distances greater than one diameter from the penetrator nose.† The stress distribution over the cross-section at these locations depends only on the resultant forces applied to the end of the structure. Thus, the simulation technique need only produce the resultant axial and lateral loading forces with the appropriate time-history but need not produce a particular load distribution.

* Further testing using this technique, and an analysis of the impact response, are being performed under Contract DNA001-74-C-0140.

† M. L. Anthony, "Impact of Earth Penetrator Models into Simulated Rock Targets," Martin Marietta Aerospace Company, Final Report for Contract DNA001-75-C-0161, November 1975.

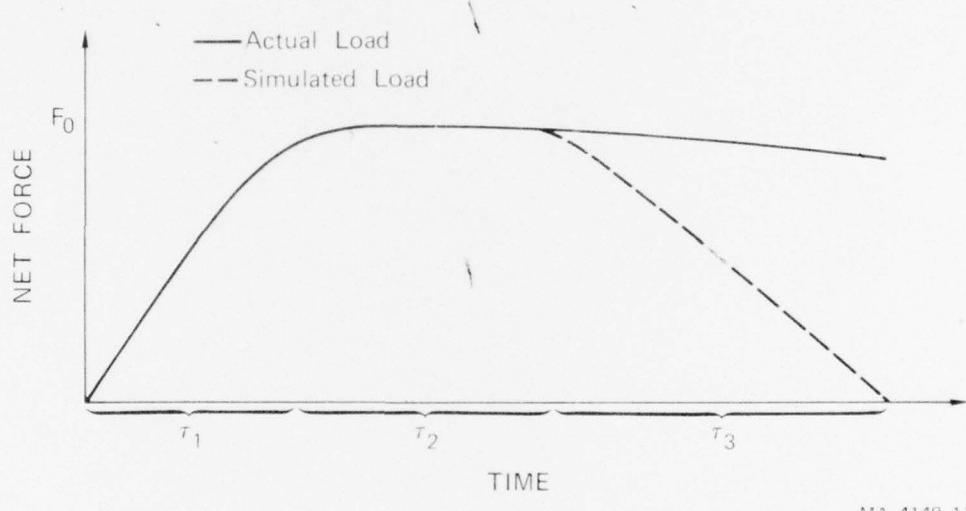
Both calculated impact loads* and measured acceleration response[†] show that the resultant force-history for normal impact consists of two distinct parts, as Figure 1 illustrates: an approximately linear rise to a peak over the time τ_1 required for the structure to penetrate to its full diameter, and a very gradual decay associated with the rigid body deceleration of the structure. For a nominal full-scale structure [6 in. (15.24 cm) in diameter, 60 in. (152.4 cm) long, and weighing 400 lbs. (181 kg)] impacting sandstone at 1500 ft/sec (457 m/sec), the loading rise time is about 1 msec and the peak force is about 500,000 lbs. (2224 kN). For impacts with nonzero angle of obliquity or angle of attack, a lateral force is also applied to the structure. In the simulation technique described here, it was assumed that the lateral load is proportional to the axial load (i.e., that F_L/F_A is constant with respect to time). Since an earth penetrating structure would fail during the load rise time or at about the time the load reaches its peak, the simulation technique must produce the axial and lateral loading forces until they reach their peak values. A simulated impact load history, in the axial or lateral direction, is illustrated in Figure 1, which shows a linear increase in amplitude during τ_1 , a constant or slowly decaying history after the peak value for a time τ_2 , and a decay over a time τ_3 .

APPROACH

A load simulation device to meet these requirements was developed for a nominal scale factor of 1/4. For this scale factor, a device was designed to produce a simulated load such as that shown in Figure 1 within the nominal ranges: $0 \leq F_o \leq 35,000$ lb. (155,700 N), $100 < \tau_1 < 500 \mu\text{sec}$, $100 < \tau_2 < 200 \mu\text{sec}$, $300 < \tau_3 < 1000 \mu\text{sec}$. These loads are

* "Internal Response in Earth Penetrators," Presented by K. Kreyenhagen, California Research and Technology, at the DNA Earth Penetration Technology Review Meeting, October 1975.

† Paul F. Hadala, "Evaluation of Empirical and Analytical Procedures Used for Predicting the Rigid Body Motion of an Earth Penetrator," Waterways Experimental Station Paper S-75-15, June 1975.



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FIGURE 1 IMPACT LOAD-TIME HISTORY ON EARTH-PENETRATOR STRUCTURES

produced with an explosive loading technique similar to that used successfully in other applications where a prescribed load history was required.

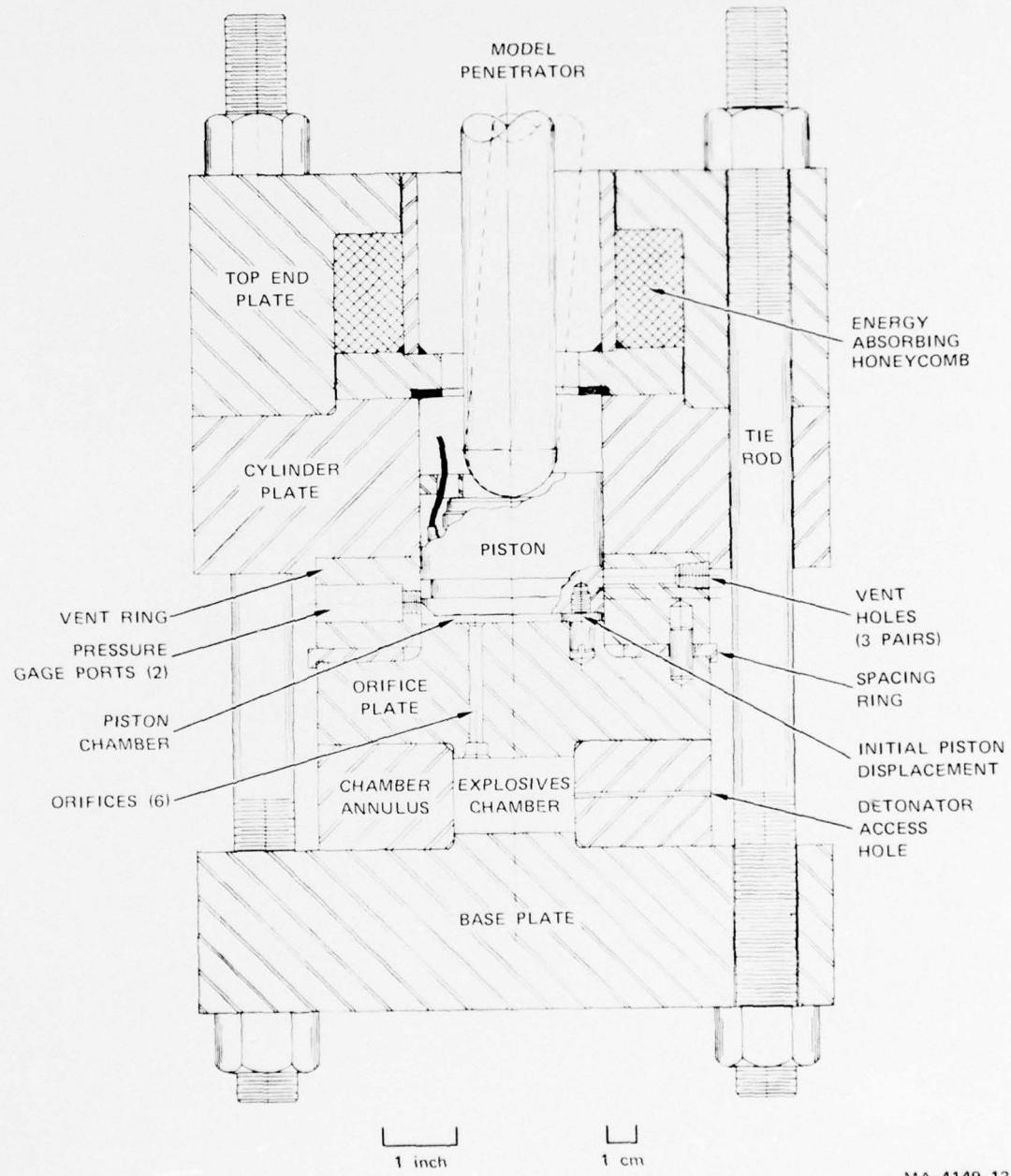
In the current load-simulation application, the controlled flow of high-pressure gases from a confined explosion produces the desired pressure pulse in a cylinder containing a piston. The piston transmits the load to the model structure. Since the model structure is initially at rest, the total kinetic energy associated with this load-simulation technique is substantially less than that of reverse ballistics. Also, starting the model at rest allows hard-wired measurement of the loads and strains.

LOAD SIMULATION DEVICE

Operation--Figure 2 is a sectioned assembly drawing of the fixture in configuration for simulating normal impact loads on 1/4-scale model penetrators. The fixture operates as follows: high-pressure gaseous explosive products are produced in the explosive chamber by detonation of a solid explosive. The gas flows through an orifice plate and into a cylinder containing a piston that is in contact with the penetrator. The load is transmitted to the penetrator through the piston (the details of this interface are discussed later). The rise time τ_1 of the load can be varied by using different initial piston displacements or different orifice areas. The duration τ_2 of the constant load can be varied by using vent holes at different locations along the cylinder. The decay time τ_3 can be varied by using different size vent holes.

The pulse produced by a given geometry may be predicted using the GASLEAK computer code^{*} that models the flow of gases in a series of chambers connected by orifices. The theoretical model of the flow

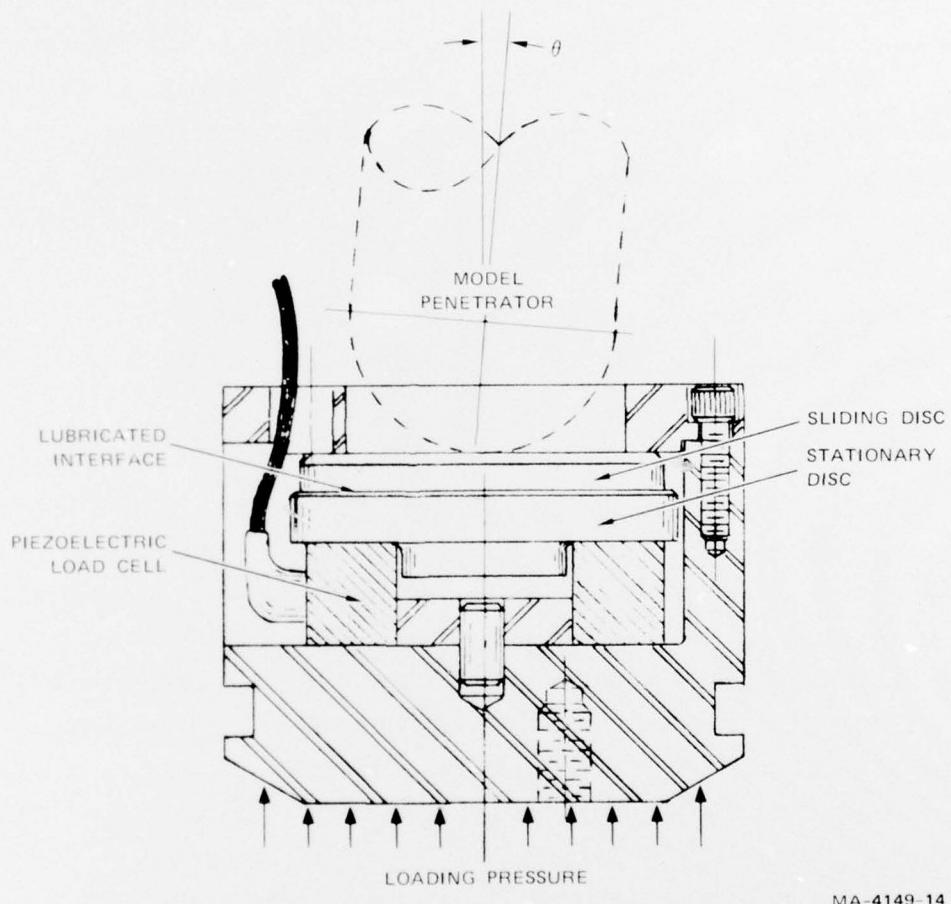
* D. J. Cagliostro, "Experiments on the Response of Hexagonal Subassembly Ducts to Radial Loads," SRI Interim Report for Argonne National Laboratory, August 1975.



assumes that (1) the duration of the loading pulse is long compared with the transit time of pressure waves in each chamber (quasi-steady flow); (2) negligible heat is transferred from the hot gas to the surrounding cylinder (adiabatic flow); (3) the hot detonation products behave as a perfect gas. Experience in other similar applications has shown excellent agreement between the theoretically predicted pressure pulse and the experimentally measured pulse.

Construction--The device is constructed of a stack of alloy steel rings and circular plates clamped together by eight tie rods. The explosive chamber is formed by a thick-walled annulus that fits between the base plate and the orifice plate. The cross-sectional area of each of the six orifices may be varied by inserting plugs drilled with the proper size hole into the recesses on the lower side of the orifice plate. The cylinder in which the piston travels is formed by the vent ring and the cylinder plate. The initial volume of the piston chamber is controlled by a spacing washer between the piston and orifice plate, which sets the initial piston displacement. The vent ring has three pairs of vent holes, each pair at a different axial location. These holes vent the piston chamber to the atmosphere as the piston passes. The size of the vent area may be varied with threaded plugs that reduce the area of the vent holes or close the holes completely. The axial location of the holes is set by the thickness of the spacing ring. Two pressure gages are mounted diametrically opposed in the vent ring to measure the chamber pressure. After the pulse is produced, the piston decelerates by impacting the energy-absorbing aluminum honeycomb.

To simulate the load on a penetrator that impacts at an angle of attack, the piston is designed to produce both axial and lateral loading and to measure directly the resultant load applied to the penetrator. The combined loading is produced by tilting the penetrator through an angle θ with respect to the piston axis, as shown in the sectioned drawing of the piston in Figure 3. The vertical force F is measured with a piezoelectric load cell (Kistler 906A). Two discs are placed between the load cell and the penetrator and the interface between



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FIGURE 3 PISTON FOR ANGULAR LOADING

them is lubricated with a high-pressure, low-friction solid lubricant* to minimize frictional forces parallel to the face of the load cell. By allowing the loaded end of the penetrator to slide across the load cell with negligible friction forces, the vertical force F is parallel to the piston axis. The axial load applied to the model SBM structure is then $F \cdot \cos\theta$, and the lateral load is $F \cdot \sin\theta$.

Figure 4 shows the assembled device with a scale model SBM structure in position for a normal impact simulation. After the load simulation, the penetrator leaves the device and is stopped by an external energy absorber (aluminum honeycomb or Styrofoam) located in a 5-ft-long (1.52-m-long) safety shroud. The shroud ensures containment of the model penetrator after the simulation. Figure 5 shows the device with the safety shroud in place for testing.

The fixture can also be used to test larger models. In this case, two parts (the piston and the top end plate) would need to be changed.

EXPERIMENTS WITH PISTON

A series of 11 tests was conducted with the loading device but without a model penetrator. The purpose of these tests was to check the operation under simplified conditions and to compare the piston chamber pressure and the rigid body motion of the piston with the motion predicted by the GASLEAK code. In all tests, the high explosive used was a mixture of PETN† and hollow glass microspheres (90% and 10%, respectively, by weight). The explosive was detonated by a mild detonating fuse that entered the explosives chamber through a small hole in the chamber annulus. The piston chamber pressure was measured with two piezoelectric pressure gages (PCB 113A) mounted in the vent ring 180 degrees apart. An accelerometer (Endevco 2225) mounted on the top

* Several brands used, most frequently SprayKote, manufactured by Dow Corning.

† PETN ($C_5H_8O_{12}N_4$) pentaerythritol tetranitrate.

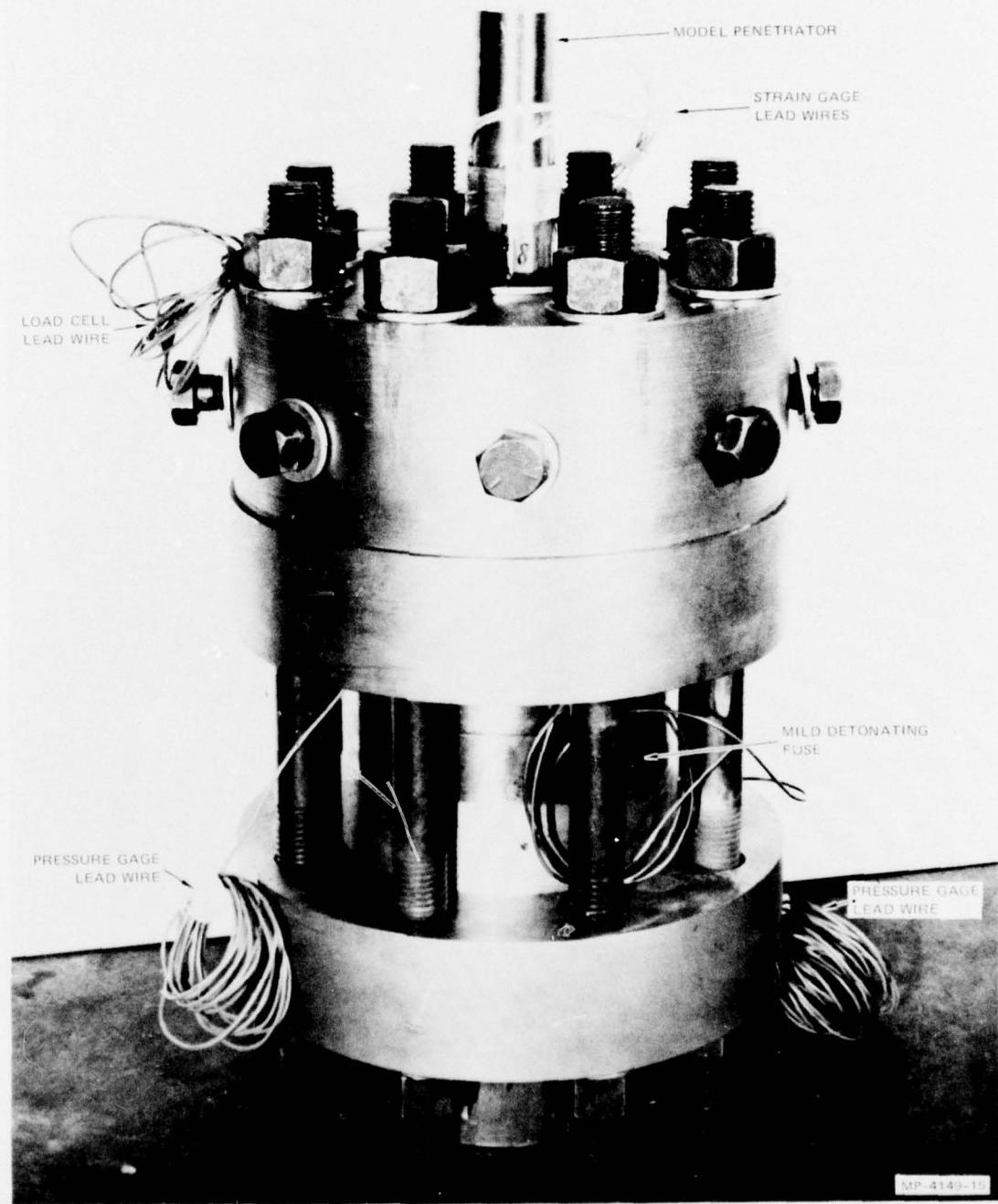


FIGURE 4 ASSEMBLED TEST FIXTURE FOR SIMULATING IMPACT LOADS

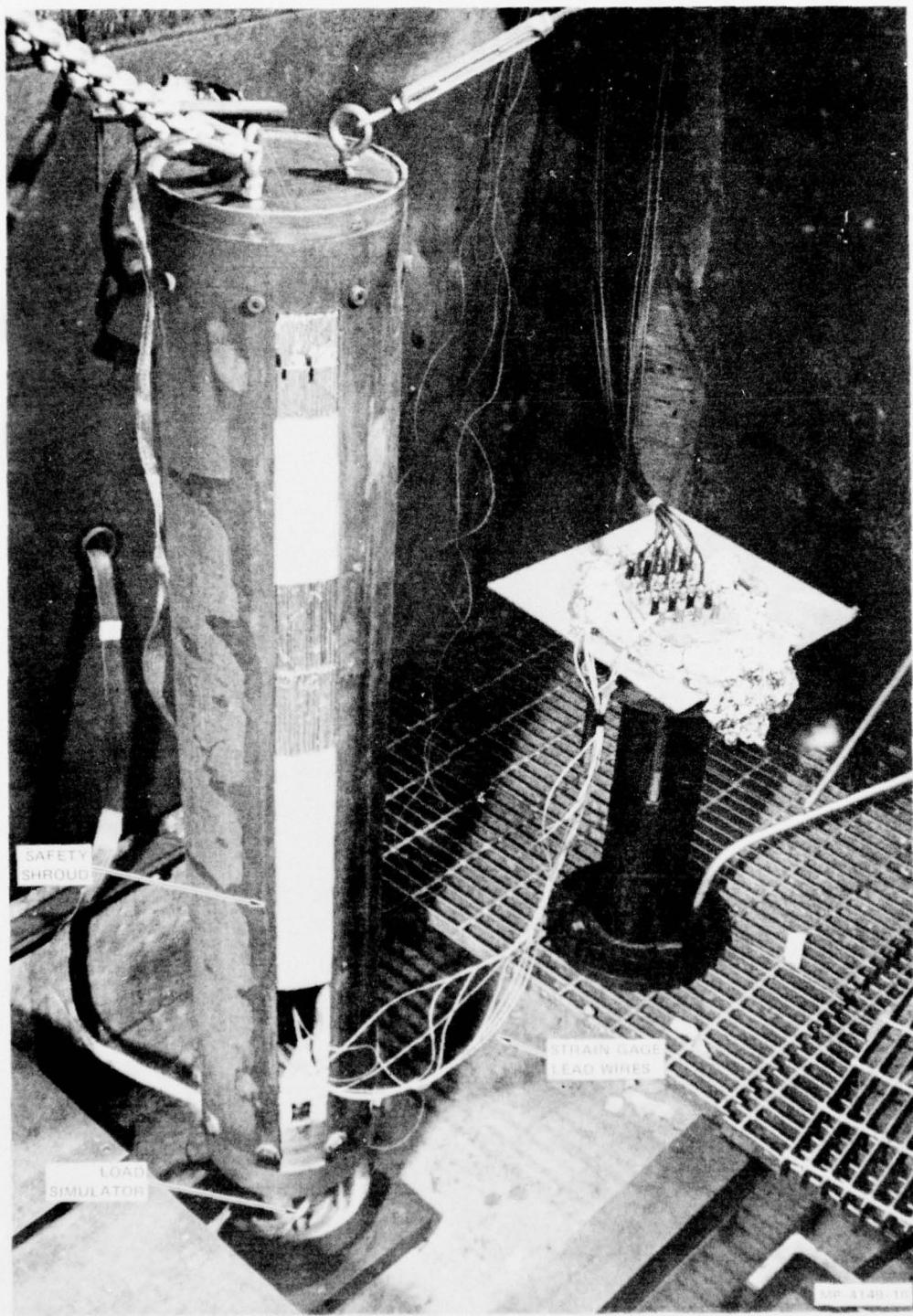


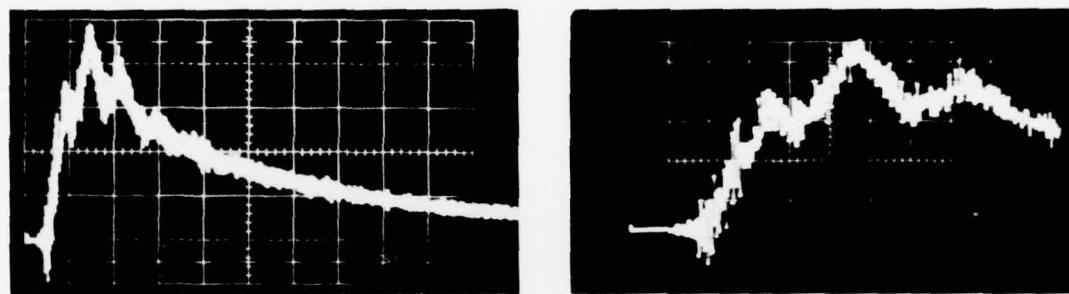
FIGURE 5 FIXTURE READY FOR TESTING

face of the piston recorded the axial acceleration of the piston during the tests. A 1/16-in.-thick (0.16-cm-thick) rubber pad was bonded between the accelerometer and the piston to suppress ringing in the accelerometer.

Figure 6 shows the chamber pressure and piston acceleration in Test 11, without a model penetrator. The device set-up parameters were 1 gram 90/10 PETN/ μ sphere explosive charge; all orifice plate holes open; 0.060-in. (0.152-cm) initial piston displacement; bottom two pairs of vent holes closed, top pair open; and no spacing ring. The pressure measured at this point oscillates because of pressure waves in the gas, Figure 6(a). However the average pressure over the piston face produces a smooth piston acceleration history, Figure 6(b). The high-frequency oscillations in the acceleration record are caused by the accelerometer and flexible rubber mount vibrating as a simple mass-spring system.

Figure 6 illustrates that, in the absence of a model penetrator, the desired type of pulse is produced: a steep linear rise, an approximately level plateau, and a gradual decay at a rate slower than the rise.

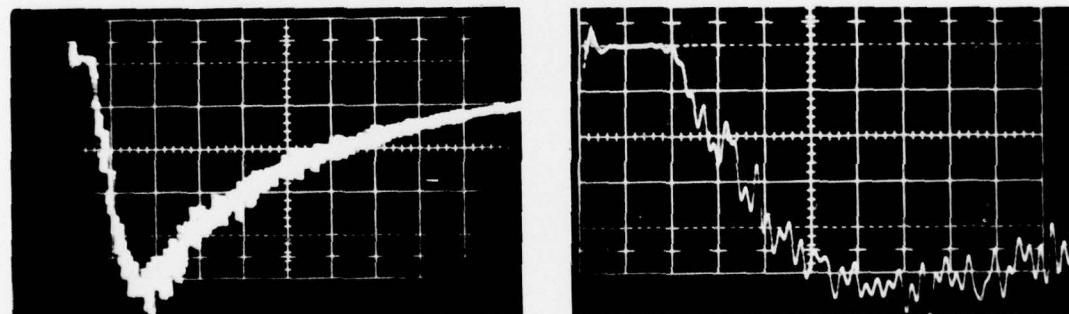
Other tests in the calibration series show that the impact load-time history can be varied by changing the geometry of the device, as described above. For example, Figure 7 shows the results from Test 9 in which the initial piston displacement and explosive charge were increased from those of Test 11. The device set-up parameters for Test 9 were 2 grams 90/10 PETN/ μ sphere explosive charge; all orifice plate holes open; 0.300-in. (0.762-cm) initial piston displacement; bottom two pairs of vent holes closed, top pair open; and no spacing ring. Comparing Test 9 with Test 11, we see a longer rise time due to the greater initial piston displacement, and higher peak pressure and acceleration due to the larger explosive charge. Table 1 lists the complete series of calibration tests conducted without a model penetrator.



400 psi/cm (2758 kPa/cm) 200 μ s/cm

(a) PRESSURE GAGE I (POSITIVE UPWARD)

400 psi/cm (2758 kPa/cm) 50 μ s/cm



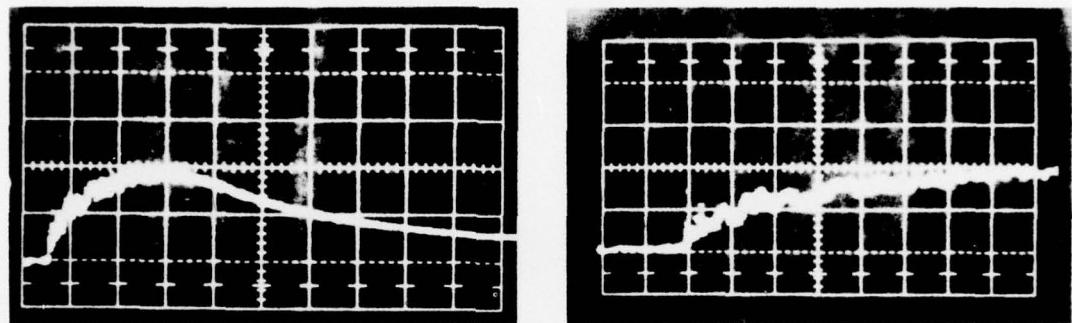
500 g/cm 200 μ s/cm

(b) PISTON ACCELERATION (POSITIVE DOWNWARD)

500 g/cm 50 μ s/cm

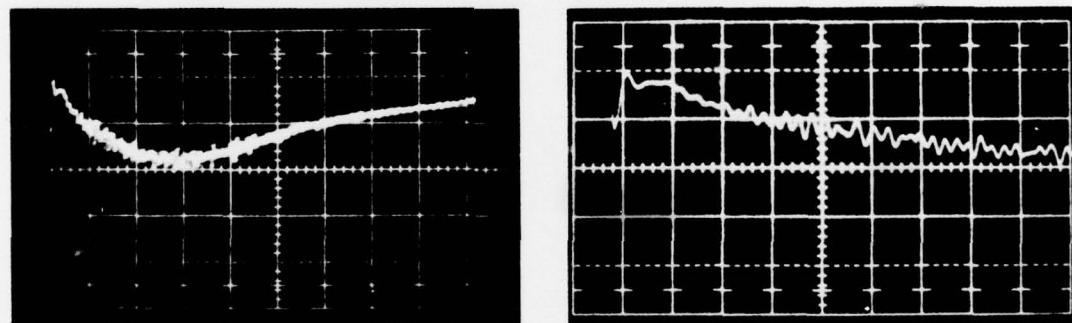
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FIGURE 6 TEST 11 – CALIBRATION TEST WITHOUT MODEL PENETRATOR



1000 psi/cm (6894 kPa/cm) 200 μ s/cm 1000 psi/cm (6894 kPa/cm) 50 μ s/cm

(a) PRESSURE GAGE I (POSITIVE UPWARD)



2000 g/cm 200 μ s/cm 2000 g/cm 50 μ s/cm

(b) PISTON ACCELERATION (POSITIVE DOWNWARD)

MP-4149-17

FIGURE 7 TEST 9—CALIBRATION TEST WITHOUT MODEL PENETRATOR

Table I
RESULTS OF CALIBRATION EXPERIMENTS WITHOUT MODEL PENETRATOR

Test No.	Date	Charge Massa (gm)	Initial Piston Displacement (cm)	Vent Holes	Peak Pressure ^e (KPa)	Peak Acceleration (g)	Rise Time ^g (usec)
1	3-12-76	0.66 ^b	0.193		5,790		f
2	3-15-76	0.66 ^b	0.193		6,070	1,700	100
3	3-26-76	0.543	0.457	c	4,140	1,050	180
4	3-26-76	0.543	0.457		3,650	850	170
5	3-29-76	1.086	0.457		7,760	2,000	150
6	3-29-76	1.086	0.457		7,760	2,400	110
7	3-30-76	1.086	0.457		7,070	1,800	135
8	3-30-76	2.00	0.457		14,130	4,000	120
9	3-30-76	2.00	0.762	d	11,720	3,600	240
10	4-02-76	1.00	0.305		7,450	2,000	145
11	4-02-76	1.00	0.152		10,340	2,650	115

^aFor shots 3 through 11, a small (0.02 to 0.05 gram) booster charge (DuPont Datasheet) was used; the mass listed here includes that of 90/10 PETN/Isophere charge only.

^bIncludes large (approximately 0.18 gram) booster charge (DuPont Datasheet).

^cVent hole configuration: top pair open; middle pair open; bottom pair closed.

^dVent hole configuration: top pair open; middle pair closed; bottom pair closed.

^eAverage of the two pressure gage measurements.

^fBad gage record.

^gTime to reach 75% of the peak acceleration.

CONCLUSIONS

The initial results indicate that the apparatus operates as designed. However, to determine whether the loading pulse applied to a structure accurately simulates the expected impact loads, the apparatus needs to be tested with a model earth penetrating structure in place.*

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* Additional testing is being performed under Contract DNA001-74-C-0140.

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